

REAL-TIME, PROFESSIONAL GRADE, IN-PICTURE 3D MEASUREMENT.

Take a picture. Measure anything.

The BLK3D captures images and places precise measurements at your fingerprints Share images and measurements in multiple formats.



The art of photogrammetry. Simplified.

Unmatched combination of a calibrated stereo-camera, advanced algorithms and real-time edge computing fused with leading Electronic Distance Measurement technology.



For more information, visit:

www.BLK3D.com

All specifications are subject to change without notice. All accuracy specifications are one sigma unless otherwise noted. Copyright Leica Geosystems AG, Heerbrugg, Switzerland 2018.

VERTICA





GENERAL SPECIFICATIONS

| Dimensions (H x W x D) | 180.6 x 77.6 x 27.1 mm (7.11 x 3.06 x 1.07 in) |
|---------------------------------------|--|
| Weight (with rechargeable battery) | 480 g (17 oz) |
| Temperature range | Storage: -25 to 60 °C (-13 to 140 °F) Operation: -10 to 50 °C (14 to 122 °F) Charging: 0 to 40 °C (32 to 104 °F) |
| Tripod adapter | Supports 1/4-20 UNC screw adapters |

TECHNOLOGY

| Operating system | Android 7.1.2 (Nougat) |
|------------------------------------|---|
| Processor (with integrated GPU) | Snapdragon 820E QuadCore (2.35 GHz) |
| RAM Memory | 4 GB |
| Real-time Processor | STM32F446 |
| Screen | 5.0" IPS, HD 720x1280 LCD capacitive multi-touch screen, chemically strengthened, brightness: 450 cd/m² |
| Stereo camera | Pixels: 2 x 10 MP (15.8 cm diagonal base line) Field of view: 80° Focal length: 4.0 mm (22 mm in 35 mm equiv. in 1:1) Aperture: F3.0 |
| EDM camera | Pixels: 2 MP Field of view: 14° |
| I/O | USB Type-C 1.0 for data transfer and charging (water- resistant), integrated speaker and microphone |
| Keyboard | Three physical buttons (Power, Laser/Photo capture, Photo capture), four touch buttons (Back, Home, Recents, Laser/Photo capture) |
| Additional sensors | Compass, 3D accelerometer and 3D gyroscope |
| Laser class | 2 |
| Laser type | 655 nm, 0.95 mW |

STORAGE

| Internal storage | 64 GB (equals 14000 single-shot or 5000 multi-shot 3D images) |
|------------------|--|
|------------------|--|

COMMUNICATION

| Bluetooth® Smart | Bluetooth v4.1 and v2.1 Radiated power: 1.78 mW (BLE) Radiated power: 10.00 mW (BT classic) Frequency: 2402-2480 MHz |
|------------------|---|
| Wireless LAN | Standard: 802.11 b/g/n Radiated power: 6.31 mW Frequency: 2412-2472 to 2412-2462 MHz |
| GPS | A-GPS and GLONASS |

POWER MANAGEMENT

| Battery | Rechargable battery pack Li-ion (3.80 V, 3880 mAh, 14.7 Wh) |
|------------------|---|
| Power management | AC adapter (input: 100-240 V AC) External charger (input: 100-240 V AC) (optional) |
| Charge time | < 3.5 h (with AC adaptor) < 5h (with optional external charger) |
| Operating time | Typical capture: 4h / 220 multi-shot captures ¹ Continuous capture: 2.5 h /1000 single-shot captures ¹ Laser measurements: 6.5 h / 9500 laser measurements Auto power off: after 3 h in sleep mode |

 ${}^{\eta}\text{Wi-Fi} \circledast$ off, Bluetooth \circledast off, flash off, screen brightness 50%.

²⁾ Multi-shot with recommended baseline length (all except 2.5 m 2D).

³⁾ Measurement precision, accuracy, and reliability are dependent upon various factor including distance and position to object, baseline length, texture of object, light conditions, ambient temperature, calibration etc. Figures quoted assume normal to favourable conditions at close range and are subject to change.

- ⁴⁾ Applies to 100 % target reflectivity (white painted wall), low background illumination, 25 °C.
- $^{\rm 5)}$ Applies to 10 to 100 % target reflectivity, high background illumination, 10 °C to + 50 °C. ^{e)} Tolerances apply to ranges from 0.05 m to 10 m with a confidence level of 95%. The maximum tolerance may deteriorate to 0.1 mm/m between 10 m to 30 m, to 0.20 mm/m between 30 m to 100 m and to 0.30 mm/m for distances above 100 m.

LASER DISTANCE MEASUREMENT

| Accuracy with favourable conditions ⁴ | ± 1.0 mm (0.04 in) ⁶ |
|---|----------------------------------|
| Accuracy with unfavourable conditions $^{\scriptscriptstyle 5}$ | ± 2.0 mm (0.08 in) ⁶ |
| Range with favourable conditions ⁴ | 250 m (820 ft) |
| Range with unfavourable conditions ⁵ | 120 m (394 ft) |
| Smallest unit displayed | 0.1 mm (1/32 in) |
| X-Range Power Technology™ | yes |
| 0 laser point at distances | 6 / 30 / 60 mm (10 / 50 / 100 m) |

TILT MEASUREMENT

| Measuring tolerance to laser beam ⁷ | ± 0.2° |
|--|--------|
| Measuring tolerance to housing ⁷ | ± 0.2° |
| Range | 360° |

P2P MEASUREMENT WITH DST 360 (OPTIONAL)

| Working range vertical sensor | -64° to > 90° |
|--|---------------|
| | |
| Accuracy vertical sensor up to | ± 0.1° |
| Working range horizontal sensor | 360° |
| working range nonzontal sensor | 300 |
| Accuracy horizontal sensor up to | ± 0.1° |
| | |
| Tolerance P2P function at distances (combination | ± 2 mm / 2 m |
| of sensors and distance measuring) approx. | ± 5 mm / 5 m |
| of sensors and distance measuring approx. | ± 10 mm /10 m |
| | . 59 |
| Levelling range | ± 5° |

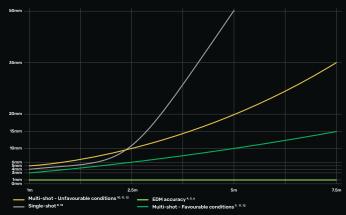
SOFTWARE OPTIONS OVERVIEW

Minimum system requirements

| BLK3D Mobile | | |
|-------------------------------------|---|--|
| BLK3D Mobile (included) | Reality Capture, Laser, Organiser, 3D Image export to pdf and jpg | |
| Sketch & Document Option (optional) | Sketch Plan , P2P Measure, Smart Room, Plan export to pdf, jpg, DXF and DWG (2D/3D/raw) | |
| | | |
| BLK3D Desktop | | |
| BLK3D Desktop Base (optional) | Organiser, Measure, working with plans | |
| 3D Model Option (optional) | 3D Modelling on 3D Images incl. export to DXF and DWG (3D) | |

Windows 8.1, 10 with 64-bit; 6 GB RAM

IN-PICTURE MEASUREMENT ACCURACY TABLE



 $^{\prime\prime}$ After user calibration. Additional angle related deviation of ±0.0.1° per degree up to ±45° in each auadrant.

⁸⁾ A single-shot is only recommended up to a distance of 2.5 meters to the target object ⁹⁾ 2D distances

¹⁰⁾ Long 2D distances (corner to corner measurements in a 3D Image) and 3D distances

¹¹⁾ Multi-shot with recommended baseline length of 10% of the distance to the target object ¹²⁾ Measurement precision, accuracy, and reliability are dependent upon various factors including distance and position to object, baseline length, texture of object, light conditions, ambient temperature, calibration etc. Figures quoted are subject to change.